

VRbot Voice Recognition Module



Data Sheet Ver. 1.0

Product Description

VRbot Module is designed to easily add versatile voice command functionality to robots (e.g. ROBONOVA-I, RoboZak, POP-BOT, ...) or any other host (e.g. PIC, Arduino boards, ...).

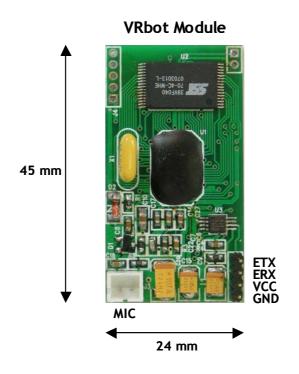
VRbot features:

- A host of built-in speaker independent (SI) commands for ready to run basic controls
- Supports up to 32 user-defined Speaker Dependent (SD) triggers or commands as well as Voice Passwords. SD custom commands can be spoken in ANY language.
- Easy-to-use and simple Graphical User Interface to program Voice Commands
- Languages currently supported for SI commands: English U.S., Italian, Japanese and German. More languages available in the near future.
- Module can be used with any host with an UART interface (powered at 3.3V 5V)
- Simple and robust documented serial protocol to access and program through the host board



Technical specifications

Physical dimensions and pin assignment



Pin number	Pin name	Type (Input/Output)	Description		
1	GND	-	Ground		
2	VCC	I	Voltage DC input		
3	ERX	I	Serial Port Receive Data (TTL level)		
4	ETX	0	Serial Port Transmit Data (TTL level)		

Recommended Operating Conditions

Symbol	Parameter		Тур	Max	Unit
VCC	Voltage DC Input		5.0	5.5	V
Та	Ambient Operating Temperature Range		25	70	Ĉ
ERX	Serial Port Receive Data	0	-	VCC	V
ETX	Serial Port Transmit Data	0	-	VCC	V

Power Supply Requirements

Symbol	Parameter	Min	Тур	Max	Unit
I _{Sleep}	Sleep current		< 1		mA
I _{Oper}	Operating current		12		mA

Communications

Adjustable Asynchronous Serial Communication:

- Baud Rate: **9600** (default), 19200, 38700, 57600, 115200
- 8 Data bits
- No parity
- 1 Stop bit

Communications are established using the VRbot protocol. Refer to the appropriate Document available on www.veeaR.eu.

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Go to www.VeeaR.eu for updated documents and samples!