specification

ELECTRICAL

Specification Standard

Resistance Range...... 1K Ohms-10K Ohms Resistance Tolerance Std. Yield ± 20%

Special yield = 1-10%

Resolution varies with actuator

Open circuit resistance

Insulation 10 mega ohms

Dielectric Value..... No affect @ 500 VAC, 1 minute

Power Rating...... 1 watt max

MECHANICAL

Specification Standard

Operating life cycles..... > or = 1 million/5 million (Hot Pot)

Actuation force...... 3-24 oz.

Actuator Variable

ENVIRONMENTAL

Specification

Temperature

Storage

Operating...

Humidity...

Shock

Vibration

Altitude

Storage

Operatin

-65° C to + 85° C/ >85° C (Hot Pot)

-45° C to + 75° C/ >85° C (Hot Pot)

No affect @ 95% RH

No closure>10msec @ 100g half-sine on four sides

No closure>10msec@1 hour random sine test

No affect @ 24 hr and 93%

0-50,000 ft.

0-15,000 ft.



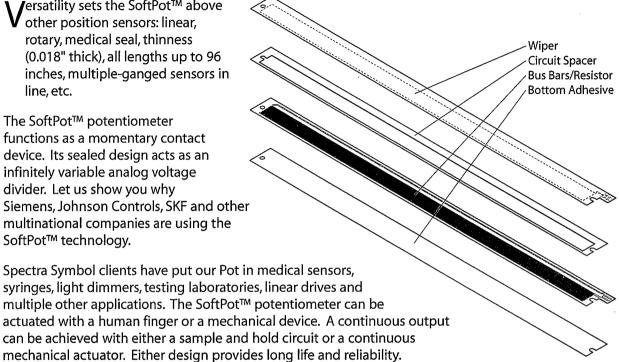
3101 West 2100 South Salt Lake City, Utah 84119 801-972-8012

. G- ペラ-2283 (toll-free)pectrasymbol.com



ersatility sets the SoftPot™ above other position sensors: linear, rotary, medical seal, thinness (0.018" thick), all lengths up to 96 inches, multiple-ganged sensors in line, etc.

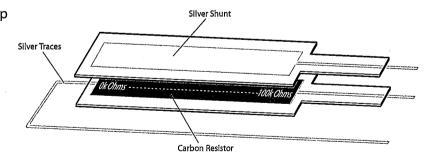
The SoftPot™ potentiometer functions as a momentary contact device. Its sealed design acts as an infinitely variable analog voltage divider. Let us show you why Siemens, Johnson Controls, SKF and other multinational companies are using the SoftPot™ technology.



SoftPot™ Design & Construction:

The SoftPot™ is simple: a wiper potentiometer that is sealed. It has three traces extending from the resistive "active area," one acting as a wiper, another trace showing voltage from one side of the pot and the third trace from the other side of the active area, as diagramed:

- ◆ The SoftPot™ acts as a voltage divider once the top and bottom circuits close, sending resistance signals from the contact point in opposite directions, using separate lower traces
- ◀ A Rheostat has only one trace on the bottom layer



Tolerances:

- ◀ **Total Resistance** is the resistance reading from one side of the carbon element to the other. Our standard is +/-20%
- **◀ Linearity** is discussed in terms of independent linearity and the variance is determined in reference to the average position
- ◀ **Resolution**, meaning the smallest increment of movement, is infinite and will produce varying output to the degree of width in the actuator

